
New Integrality Gap Results for the Firefighters Problem on Trees

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Abstract In the firefighter problem on trees, we are given a tree $G = (V, E)$ together with a vertex $s \in V$ where the fire starts spreading. At each time step, the firefighters can pick one vertex while the fire spreads from burning vertices to all their neighbors that have not been picked. The process stops when the fire can no longer spread. The objective is to find a strategy that maximizes the total number of vertices that do not burn. This is a simple mathematical model, introduced in 1995, that abstracts the spreading nature of, for instance, fire, viruses, and ideas. The firefighter problem is NP-hard and admits a $(1 - 1/e)$ approximation via LP rounding. Recently, a PTAS was announced in [1].⁴

The goal of this paper is to develop better understanding on the power of LP relaxations for the firefighter problem. We first show a matching lower bound of $(1 - 1/e + \epsilon)$ on the integrality gap of the canonical LP. This result relies on a powerful *combinatorial gadget* that can be used to derive integrality gap results in other related settings. Next, we consider the canonical LP augmented with simple additional constraints (as suggested by Hartke). We provide several evidences that these constraints improve the integrality gap of the canonical LP: (i) Extreme points of the new LP are integral for some known tractable instances and (ii) A natural family of instances that are bad for the canonical LP admits an improved approximation algorithm via the new LP. We conclude by presenting a $5/6$ integrality gap instance for the new LP.

1 Introduction

Consider the following graph-theoretic model that abstracts the fire spreading process: We are given graph $G = (V, E)$ together with the source vertex s where the fire starts. At each time step, we are allowed to pick some vertices in the graph to be saved, and the fire spreads from burning vertices to their neighbors that have not been saved so far. The process terminates when the fire cannot spread any further. This model was introduced in 1995 [13] and has been used

⁴ The $(1 - 1/e)$ approximation remained the best until very recently when Adjashvili et al. [1] showed a PTAS. Their PTAS does not bound the LP gap.

extensively by researchers in several fields as an abstraction of epidemic propagation.

There are two important variants of the firefighters problem. (i) In the maximization variant (MAX-FF), we are given graph G and source s , and we are allowed to pick one vertex per time step. The objective is to maximize the number of vertices that do not burn. (ii) In the minimization variant (MIN-FF), we are given a graph G , a source s , and a terminal set $\mathcal{X} \subseteq V(G)$, and we are allowed to pick b vertices per time step. The goal is to save all terminals in \mathcal{X} , while minimizing the budget b .

In this paper, we focus on the MAX-FF problem. The problem is $n^{1-\epsilon}$ hard to approximate in general graphs [2], so there is no hope to obtain any reasonable approximation guarantee. Past research, however, has focused on sparse graphs such as trees or grids. Much better approximation algorithms are known on trees: The problem is NP-hard [15] even on trees of degree at most three, but it admits a $(1 - 1/e)$ approximation algorithm. For more than a decade [2,5,6,10,14,15], there was no progress on this approximability status of this problem, until a PTAS was recently discovered [1].

Besides the motivation of studying epidemic propagation, the firefighter problem and its variants are interesting due to their connections to other classical optimization problems:

- (Set cover) The firefighter problem is a special case of the *maximum coverage problem with group budget constraints (MCG)* [7]: Given a collection of sets $\mathcal{S} = \{S_1, \dots, S_m\} : S_i \subseteq X$, together with *group constraints*, i.e. a partition of \mathcal{S} into groups G_1, \dots, G_ℓ , we are interested in choosing one set from each group in a way that maximizes the total number of elements covered, i.e. a feasible solution is a subset $\mathcal{S}' \subseteq \mathcal{S}$ where $|\mathcal{S}' \cap G_j| \leq 1$ for every j , and $|\bigcup_{S_i \in \mathcal{S}'} S_i|$ is maximized. It is not hard to see that MAX-FF is a special case of MCG. We refer the readers to the discussion by Chekuri and Kumar [7] for more applications of MCG.
- (Cut) In a standard minimum node-cut problem, we are given a graph G together with a source-sink pair $s, t \in V(G)$. Our goal is to find a collection of nodes $V' \subseteq V(G)$ such that $G \setminus V'$ has s and t in distinct connected components. Anshelevich et al. [2] discussed that the firefighters' solution can be seen as a “cut-over-time” in which the cut must be produced gradually over many timesteps. That is, in each time step t , the algorithm is allowed to choose vertex set V'_t to remove from the graph G , and again the final goal is to “disconnect” s from t .⁵ This cut-over-time problem is exactly equivalent to the minimization variant of the firefighter problem. We refer to [2] for more details about this equivalence.

1.1 Our Contributions

In this paper, we are interested in developing a better understanding of the MAX-FF problem from the perspective of LP relaxation. The canonical LP

⁵ The notion of disconnecting the vertices here is slightly non-standard.

relaxation has been used to obtain the known $(1 - 1/e)$ approximation algorithm via straightforward independent LP rounding (each node is picked independently with probability proportional to its LP-value). So far, it was not clear whether an improvement was possible via this LP, for instance, via sophisticated dependent rounding schemes.⁶ Indeed, for the corresponding minimization variant, MIN-FF, Chalermsook and Chuzhoy designed a dependent rounding scheme for the canonical LP in order to obtain $O(\log^* n)$ approximation algorithm, improving upon an $O(\log n)$ approximation obtained via independent LP rounding. In this paper, we are interested in studying this potential improvement for MAX-FF.

Our first result refutes such possibility for MAX-FF: we show that the integrality gap of the standard LP relaxation can be arbitrarily close to $(1 - 1/e)$.

Theorem 1. *For any $\epsilon > 0$, there is an instance (G, s) (whose size depends on ϵ) such that the ratio between optimal integral solution and fractional one is at most $(1 - 1/e + \epsilon)$.*

Our techniques rely on a powerful *combinatorial gadget* that can be used to prove integrality gap results in some other settings studied in the literature. In particular, in the b -MAX-FF problem, the firefighters can pick up to b vertices per time step, and the goal is to maximize the number of saved vertices. We provide an integrality gap of $(1 - 1/e)$ for the b -MAX-FF problem for every constant $b \in \mathbb{N}$, thus matching the algorithmic result of [9]. In the setting where an input tree has degree at most $d \in [4, \infty)$, we show an integrality gap result of $(1 - 1/e + O(1/\sqrt{d}))$. The best known algorithmic result in this setting was previously a $(1 - 1/e + \Omega(1/d))$ approximation due to [14].

Motivated by the aforementioned negative results, we search for a stronger LP relaxation for the problem. We consider adding a set of valid linear inequalities, as suggested by Hartke [12]. We show the following evidences that the new LP is a stronger relaxation than the canonical LP.

- Any extreme point of the new LP is integral for the tractable instances studied by Finbow et al. [11]. In contrast, we argue that the canonical LP does not satisfy this integrality property of extreme points.
- A family of instances, capturing the integrality gap instances of Theorem 1, admits a better than $(1 - 1/e)$ approximation algorithm via the new LP.
- When the LP solution is near-integral, e.g. for half-integral solutions, the new LP is provably better than the old one.

Our results are the first rigorous evidences that Hartke’s constraints lead to improvements upon the canonical LP. All the aforementioned algorithmic results exploit the new LP constraints in dependent LP rounding procedures. In particular, we propose a two-phase dependent rounding algorithm, which can be used in deriving the second and third results. We believe the new LP has an integrality gap strictly better than $(1 - 1/e)$, but we are unable to analyze it.

⁶ Cai, Verbin, and Yang [5] claimed an LP-respecting integrality gap of $(1 - 1/e)$, but many natural rounding algorithms in the context of this problem are not LP respecting, e.g. in [6].

Finally, we show a limitation of the new LP by presenting a family of instances, whose integrality gap can be arbitrarily close to $5/6$. This improves the known integrality gap ratio [12], and puts the integrality gap answer somewhere between $(1 - 1/e)$ and $5/6$. Closing this gap is, in our opinion, an interesting open question.

Organization: In Sect. 2, we formally define the problem and present the LP relaxation. In Sect. 3, we present the bad integrality gap instances. We present the LP augmented with Hartke’s constraints in Sect. 4 and discuss the relevant evidences of its power in comparison to the canonical LP. Some proofs are omitted for space constraint, and are presented in the full version.

Related results: King and MacGillivray showed that the firefighter problem on trees is solvable in polynomial time if the input tree has degree at most three, with the fire starting at a degree-2 vertex. From exponential time algorithm’s perspective, Cai et al. showed $2^{O(\sqrt{n} \log n)}$ time, exact algorithm. The discrete mathematics community pays particularly high attention to the firefighter problem on grids [10,16], and there has also been some work on infinite graphs [13].

The problem also received a lot of attention from the parameterized complexity perspectives [3,5,8] and on many special cases, e.g., when the tree has bounded pathwidth [8] and on bounded degree graphs [4,8].

Recent update: Very recently, Adjiashvili et al. [1] showed a polynomial time approximation scheme (PTAS) for the MAX-FF problem, therefore settling the approximability status. Their results, however, do not bound the LP integrality gap. We believe that the integrality gap questions are interesting despite the known approximation guarantees.

2 Preliminaries

A formal definition of the problem is as follows. We are given a graph G and a source vertex s where the fire starts spreading. A *strategy* is described by a collection of vertices $\mathcal{U} = \{u_t\}_{t=1}^n$ where $u_t \in V(G)$ is the vertex picked by firefighters at time t . We say that a vertex $u \in V(G)$ is *saved* by the strategy \mathcal{U} if for each path $P = (s = v_0, \dots, v_z = u)$ from s to u , we have $v_i \in \{u_1, \dots, u_i\}$ for some $i = 1, \dots, z$. A vertex v not saved by \mathcal{U} is said to be a *burning vertex*. The objective of the problem is to compute \mathcal{U} so as to maximize the total number of saved vertices. Denote by $\text{OPT}(G, s)$ the number of vertices saved by an optimal solution.

When G is a tree, we think of G as being partitioned into layers L_1, \dots, L_λ where λ is the height of the tree, and L_i contains vertices whose distance is exactly i from s . Every strategy has the following structure.

Proposition 1. *Consider the firefighters problem’s instance (G, s) where G is a tree. Let $\mathcal{U} = \{u_1, \dots, u_n\}$ be any strategy. Then there is another strategy $\mathcal{U}' = \{u'_t\}$ where u'_t belongs to layer t in G , and \mathcal{U}' saves at least as many vertices as \mathcal{U} does.*

We remark that this structural result holds only when G is a tree.

LP Relaxation: This paper focuses on the linear programming aspect of the problem. For any vertex v , let P_v denote the (unique) path from s to v , and let T_v denote the subtree rooted at v . A natural LP relaxation is denoted by (LP-1): We have variable x_v indicating whether v is picked by the solution, and y_v indicating whether v is saved.

$$\begin{array}{ll}
\text{(LP-1)} & \text{(LP-2)} \\
\max \sum_{v \in V} y_v & \max \sum_{v \in \mathcal{X}} y_v \\
\sum_{v \in L_j} x_v \leq 1 \text{ for each layer } j & \sum_{v \in L_j} x_v \leq 1 \text{ for each layer } j \\
y_v \leq \sum_{u \in P_v} x_u \text{ for each } v \in V & y_v \leq \sum_{u \in P_v} x_u \text{ for each } v \in \mathcal{X} \\
x_v, y_v \in [0, 1] \text{ for each } v & x_v, y_v \in [0, 1] \text{ for each } v
\end{array}$$

Let $\text{LP}(T, s)$ denote the optimal fractional LP value for an instance (T, s) . The integrality gap $\text{gap}(T, s)$ of the instance (T, s) is defined as $\text{gap}(T, s) = \text{OPT}(T, s) / \text{LP}(T, s)$. The integrality gap of the LP is defined as $\inf_T \text{gap}(T, s)$.

Firefighters with terminals: We consider a more general variant of the problem, where we are only interested in saving a subset \mathcal{X} of vertices, which we call *terminals*. The goal is now to maximize the number of saved terminals. An LP formulation of this problem, given an instance (T, v, \mathcal{X}) , is denoted by (LP-2). The following lemma argues that these two variants are “equivalent” from the perspectives of LP relaxation.

Lemma 1. *Let (T, \mathcal{X}, s) , with $|\mathcal{X}| > 0$, be an input for the terminal firefighters problem that gives an integrality gap of γ for (LP-2), and that the value of the fractional optimal solution is at least 1. Then, for any $\epsilon > 0$, there is an instance (T', s') that gives an integrality gap of $\gamma + \epsilon$ for (LP-1).*

Proof. Let $M = 2|V(T)|/\epsilon$. Starting from (T, \mathcal{X}, s) , we construct an instance (T', s') by adding M children to each vertex in \mathcal{X} , so the number of vertices in T' is $|V(T')| = |V(T)| + M|\mathcal{X}|$. We denote the copies of \mathcal{X} in T' by \mathcal{X}' and the set of their added children by \mathcal{X}'' . The root of the new tree, s' , is the same as s (the root of T .) Now we argue that the instance (T', s') has the desired integrality gap, i.e. we argue that $\text{OPT}(T', s') \leq (\gamma + \epsilon)\text{LP}(T', s')$.

Let (x', y') be an integral solution to the instance (T', s') . We upper bound the number of vertices saved by this solution, i.e. upper bounding $\sum_{v \in V(T')} y'_v$. We analyze three cases:

- For a vertex $v \in V(T') \setminus \mathcal{X}''$, we upper bound the term y'_v by 1, and so the sum $\sum_{v \in V(T') \setminus \mathcal{X}''} y'_v$ by $|V(T)|$.
- Now define $\mathcal{X}' \subseteq \mathcal{X}''$ as the set of vertices v for which $y'_v = 1$ but $y'_u = 0$ for the parent u of v . This means that $x'_u = 1$ for all vertices in \mathcal{X}' .

Notice that $\sum_{v \in \tilde{\mathcal{X}}} y'_v \leq |\mathcal{X}|$: We break the set $\tilde{\mathcal{X}}$ into $\{\tilde{\mathcal{X}}_u\}_{u \in V(T')}$ where

$\tilde{\mathcal{X}}_u = \{v \in \tilde{\mathcal{X}} : u \text{ is the parent of } v\}$. The LP constraint guarantees that $\sum_{v \in \tilde{\mathcal{X}}_u} y'_v = \sum_{v \in \tilde{\mathcal{X}}_u} x'_v \leq 1$ (all vertices in $\tilde{\mathcal{X}}_u$ belong to the same layer.) Summing over all such $u \in \mathcal{X}'$, we get the desired bound.

- Finally, consider the term $\sum_{v \in \mathcal{X}' \setminus \tilde{\mathcal{X}}} y'_v$. Let (x^*, y^*) be an optimal fractional solution to (T, \mathcal{X}, s) for (LP-2). We only need to care about all vertices v such that $y'_u = 1$ for the parent u of v . This term is upper bounded by $M \sum_{u \in \mathcal{X}'} y'_u$, which is at most $M\gamma (\sum_{v \in \mathcal{X}} y_v^*)$, due to the fact that the solution (x', y') induces an integral solution on instance (T, \mathcal{X}, s) .

Combining the three cases, we get $|V(T)| + |\mathcal{X}| + M\gamma (\sum_{v \in \mathcal{X}} y_v^*) \leq M + \gamma M (\sum_{v \in \mathcal{X}} y_v^*) \leq M(\gamma + \epsilon) (\sum_{v \in \mathcal{X}} y_v^*)$, if $\sum_{v \in \mathcal{X}} y_v^* \geq 1$. Now, notice that the fractional solution (x^*, y^*) for (LP-2) on instance (T, \mathcal{X}, s) is also feasible for (LP-1) on (T', s') with at least a multiplicative factor of M times the objective value: Each fractional saving of $u \in \mathcal{X}'$ contributes to save all M children of u . Therefore, $M (\sum_{v \in \mathcal{X}} y_v^*) \leq M \cdot \text{LP}(T', s')$, thus concluding the proof.

We will, from now on, focus on studying the integrality gap of (LP-2).

3 Integrality Gap of (LP-2)

We first discuss the integrality gap of (LP-2) for a general tree. We use the following combinatorial gadget.

Gadget: A (M, k, δ) -good gadget is a collection of trees $\mathcal{T} = \{T_1, \dots, T_M\}$, with roots r_1, \dots, r_M where r_i is a root of T_i , and a subset $\mathcal{S} \subseteq \bigcup V(T_i)$ that satisfy the following properties:

- (Uniform depth) We think of these trees as having layers L_0, L_1, \dots, L_h , where L_j is the union over all trees of all vertices at layer j and $L_0 = \{r_1, \dots, r_m\}$. All leaves are in the same layer L_h .
- (LP-friendly) For any layer L_j , $j \geq 1$, we have $|\mathcal{S} \cap L_j| \leq k$ (and $|\mathcal{S} \cap L_0| = 0$). Moreover, for any tree T_i and a leaf $v \in V(T_i)$, the unique path from r_i to v must contain exactly one vertex in \mathcal{S} .
- (Integrally adversarial) Let $\mathcal{B} \subseteq \{r_1, \dots, r_M\}$ be any subset of roots. Consider a subset of vertices $\mathcal{U} = \{u_j\}_{j=1}^h$ such that $u_j \in L_j$. For $r_i \in \mathcal{B}$ and a leaf $v \in L_h \cap V(T_i)$, we say that v is $(\mathcal{U}, \mathcal{B})$ -risky if the unique path from r_i to v does not contain any vertex in \mathcal{U} . There must be at least $(1 - 1/k - \delta) \frac{|\mathcal{B}|}{M} |L_h|$ vertices in L_h that are $(\mathcal{U}, \mathcal{B})$ -risky, for all choices of \mathcal{B} and \mathcal{U} .

We say that vertices in \mathcal{S} are *special* and all other vertices are *regular*.

Lemma 2. *For any integers $k \geq 2$, $M \geq 1$, and any real number $\delta > 0$, a (M, k, δ) -good gadget exists. Moreover, the gadget contains at most $(k/\delta)^{O(M)}$ vertices.*

We first show how to use this lemma to derive our final construction. The proof of the lemma follows later.

Construction: Our construction proceeds in k phases, and we will define it inductively. The first phase of the construction is simply a $(1, k, \delta)$ -good gadget. Now, assume that we have constructed the instance up to phase q . Let $l_1, \dots, l_{M_q} \in L_{\alpha_q}$ be the leaves after the construction of phase q that all lie in layer α_q . In phase $q+1$, we take the (M_q, k, δ) -good gadget $(\mathcal{T}_q, \{r_q\}, \mathcal{S}_q)$; recall that such a gadget consists of M_q trees. For each $i = 1, \dots, M_q$, we unify each root r_i with the leaf l_i . This completes the description of the construction.

Denote by $\bar{\mathcal{S}}_q = \bigcup_{q' \leq q} \mathcal{S}_{q'}$ the set of all special vertices in the first q phases. After phase q , we argue that our construction satisfies the following properties:

- All leaves are in the same layer α_q .
- For every layer L_j , $|L_j \cap \bar{\mathcal{S}}_q| \leq k$. For every path P from the root to $v \in L_{\alpha_i}$, $|P \cap \bar{\mathcal{S}}_q| = q$.
- For any integral solution \mathcal{U} , at least $|L_{\alpha_q}|((1 - 1/k)^q - q\delta)$ vertices of L_{α_q} burn.

It is clear from the construction that the leaves after phase q are all in the same layer. As to the second property, the properties of the gadget ensure that there are at most k special vertices per layer. Moreover, consider each path P from the root to some vertex $v \in L_{\alpha_{q+1}}$. We can split this path into two parts $P = P' \cup P''$ where P' starts from the root and ends at some $v' \in L_{\alpha_q}$, and P'' starts at v' and ends at v . By the induction hypothesis, $|P' \cap \bar{\mathcal{S}}_q| = q$ and the second property of the gadget guarantees that $|P'' \cap \mathcal{S}_{q+1}| = 1$.

To prove the final property, consider a solution $\mathcal{U} = \{u_1, \dots, u_{\alpha_{q+1}}\}$, which can be seen as $\mathcal{U}' \cup \mathcal{U}''$ where $\mathcal{U}' = \{u_1, \dots, u_{\alpha_q}\}$ and $\mathcal{U}'' = \{u_{\alpha_q+1}, \dots, u_{\alpha_{q+1}}\}$. By the induction hypothesis, we have that at least $((1 - 1/k)^q - q\delta)|L_{\alpha_q}|$ vertices in L_{α_q} burn; denote these burning vertices by \mathcal{B} . The third property of the gadget will ensure that at least $(1 - 1/k - \delta)\frac{|\mathcal{B}|}{M_q}|L_{\alpha_{q+1}}|$ vertices in $L_{\alpha_{q+1}}$ must be $(\mathcal{U}'', \mathcal{B})$ -risky. For each risky vertex $v \in L_{\alpha_{q+1}}$, a unique path from the root to $v' \in \mathcal{B}$ does not contain any vertex in \mathcal{U}' , and also the path from v' to v does not contain a vertex in \mathcal{U}'' (due to the fact that it is $(\mathcal{U}'', \mathcal{B})$ -risky.) This implies that such vertex v must burn. Therefore, the fraction of burning vertices in layer $L_{\alpha_{q+1}}$ is at least $(1 - 1/k - \delta)|\mathcal{B}|/M_q \geq (1 - 1/k - \delta)((1 - 1/k)^q - q\delta)$, by induction hypothesis. This number is at least $(1 - 1/k)^{q+1} - (q+1)\delta$, maintaining the invariant.

After the construction of all k phases, the leaves are designated as the terminals \mathcal{X} . Also, $M_{q+1} \leq (k/\delta)^{2M_q}$, which means that, after k phases, M_k is at most a tower function of $(k/\delta)^2$, that is, $(k/\delta)^{2(k/\delta)^{\dots}}$ with $k-1$ such exponentiations. The total size of the construction is $\sum_q (k/\delta)^{2M_q} \leq (k/\delta)^{2M_k} = O(M_{k+1})$.

For an example construction ($k = 2$), refer to the full version.

Theorem 2. *A fractional solution, that assigns $x_v = 1/k$ to each special vertex v , saves every terminal. On the other hand, any integral solution can save at most a fraction of $1 - (1 - 1/k)^k + \epsilon$.*

Proof. We assign the LP solution $x_v = 1/k$ to all special vertices (those vertices in $\bar{\mathcal{S}}_k$), and $x_v = 0$ to regular vertices. Since the construction ensures that there

are at most k special vertices per layer, we have $\sum_{v \in L_j} x_v \leq 1$ for every layer L_j . Moreover, every terminal is fractionally saved: For any $t \in \mathcal{X}$, the path $|P_t \cap \bar{\mathcal{S}}_k| = k$, so we have $\sum_{v \in P_t} x_v = 1$.

For the integral solution analysis, set $\delta = \epsilon/k$. The proof follows immediately from the properties of the instance.

3.1 Proof of Lemma 2

We now show that the (M, k, δ) -good gadget exists for any value of $M \in \mathbb{N}$, $k \in \mathbb{N}$, $k \geq 2$ and $\delta \in \mathbb{R}_{>0}$. We first describe the construction and then show that it has the desired properties.

Construction: Throughout the construction, we use a structure which we call *spider*. A spider is a tree in which every node except the root has at most one child. If a node has no children (i. e. a leaf), we call it a *foot* of the spider. We call the paths from the root to each foot the *legs* of the spider.

Let $D = \lceil 4/\delta \rceil$. For each $i = 1, \dots, M$, the tree T_i is constructed as follows. We have a spider rooted at r_i that contains kD^{i-1} legs. Its feet are in D^{i-1} consecutive layers, starting at layer $\alpha_i = 1 + \sum_{j < i} D^{j-1}$; each such layer has k feet. Denote by $\mathcal{S}^{(i)}$ the feet of these spiders. Next, for each vertex $v \in \mathcal{S}^{(i)}$, we have a spider rooted at v , having D^{2M-i+1} feet, all of which belong to layer $\alpha = 1 + \sum_{j \leq M} D^{j-1}$. The set \mathcal{S} is defined as $\mathcal{S} = \bigcup_{i=1}^M \mathcal{S}^{(i)}$. This concludes the construction. We will use the following observation:

Observation 1. *For each root r_i , the number of leaves of T_i is kD^{2M} .*

Analysis: We now prove that the above gadget is (M, k, δ) -good. The construction ensures that all leaves are in the same layer L_α .

The second property also follows obviously from the construction: For $i \neq i'$, we have that $\mathcal{S}^{(i)} \cap \mathcal{S}^{(i')} = \emptyset$, and that each layer contains exactly k vertices from $\mathcal{S}^{(i)}$. Moreover, any path from r_i to the leaf of T_i must go through a vertex in $\mathcal{S}^{(i)}$.

The third and final property is established by the following two lemmas.

Lemma 3. *For any $r_i \in \mathcal{B}$ and any subset of vertices $\mathcal{U} = \{u_j\}_{j=1}^h$ such that $u_j \in L_j$, a fraction of at least $(1 - 1/k - 2/D)$ of $\mathcal{S}^{(i)}$ are $(\mathcal{U}, \mathcal{B})$ -risky.*

Proof. Notice that a vertex v is $(\mathcal{U}, \mathcal{B})$ -risky if \mathcal{U} is not a vertex cut separating v from \mathcal{B} . There are kD^{i-1} vertex-disjoint paths from $r_i \in \mathcal{B}$ to vertices in $\mathcal{S}^{(i)}$. But the cut \mathcal{U} induced on these paths contains at most $\sum_{i' \leq i} D^{i'-1}$ vertices (because all vertices in $\mathcal{S}^{(i)}$ are contained in the first $\sum_{i' \leq i} D^{i'-1} \leq D^{i-1} + 2D^{i-2}$ layers.) Therefore, at most $(1/k + 2/D)$ fraction of vertices in $\mathcal{S}^{(i)}$ can be disconnected by \mathcal{U} , and those that are not cut remain $(\mathcal{U}, \mathcal{B})$ -risky. \square

Lemma 4. *Let $v \in \mathcal{S}^{(i)}$ that is $(\mathcal{U}, \mathcal{B})$ -risky. Then at least $(1 - 2/D)$ fraction of descendants of v in L_α must be $(\mathcal{U}, \mathcal{B})$ -risky.*

Proof. Consider each $v \in \mathcal{S}^{(i)}$ that is $(\mathcal{U}, \mathcal{B})$ -risky and a collection of leaves \mathcal{L}_v that are descendants of vertex v . Notice that a leaf $u \in \mathcal{L}_v$ is $(\mathcal{U}, \mathcal{B})$ -risky if removing \mathcal{U} does not disconnect vertex v from u .

There are $D^{2M-i+1} \geq D^{M+1}$ vertex disjoint paths connecting vertex v with leaves in \mathcal{L}_v , while the cut set \mathcal{U} contains at most $2D^M$ vertices. Therefore, removing \mathcal{U} can disconnect at most $2/D$ fraction of vertices in \mathcal{L}_v from v . \square

Combining the above two lemmas, for each $r_i \in \mathcal{B}$, the fraction of leaves of T_i that are $(\mathcal{U}, \mathcal{B})$ -risky are at least $(1 - 1/k - 2/D)(1 - 2/D) \geq (1 - 1/k - 4/D)$. Therefore, the total number of such leaves, over all trees in \mathcal{T} , are $(1 - 1/k - \delta)|\mathcal{B}||L_\alpha|/M$.

We extend the construction to other settings in the full version.

Arbitrary number of firefighters: Let $b \in \mathbb{N}$. In the b -firefighter problem, at each time step, the firefighters may choose up to b vertices, and the fire spreads from the burning vertices to vertices that have not been chosen so far. The goal is to maximize the number of saved vertices. In this section, we show the following:

Theorem 3. *For any integer $b \in \mathbb{N}$ (independent of $|V(G)|$), the integrality gap of the canonical LP can be arbitrarily close to $(1 - 1/e)$.*

Proof. To prove this theorem, one only need to design a slightly different good gadget. That is, an (M, k, δ) -good gadget is now a collection of trees \mathcal{T} with roots r_1, \dots, r_M together with $\mathcal{S} \subseteq \bigcup V(T_i)$ that satisfy the following properties:

- All leaves of T_i are in the same layer L_h .
- For each layer L_j , we have $|\mathcal{S} \cap L_j| \leq kb$. Moreover, for any tree T_i and a leaf $v \in V(T_i)$, the unique path from r_i to v must contain at least one vertex in \mathcal{S} .
- For any subset $\mathcal{B} \subseteq \{r_1, \dots, r_M\}$ of roots and for any strategy \mathcal{U} , at least $(1 - 1/k - \delta) \frac{|\mathcal{B}||L_h|}{M}$ vertices in L_h are $(\mathcal{U}, \mathcal{B})$ -risky.

It is not hard to see that these gadgets can be used to construct the integrality gap in the same way as in the previous section. Details are omitted. \square

Bounded degrees: Iwakawa et al. showed a $(1 - 1/e + \Omega(1/d))$ approximation algorithm for the instance that has degree at most d . We show an instance where this dependence on $1/d$ is almost the best possible that can be obtained from this LP.

Theorem 4. *For every $d \geq 4$, the integrality gap of (LP-1) on degree- d graphs is $(1 - 1/e + O(1/\sqrt{d}))$.*

Proof. To prove this theorem, we construct a “bounded degree” analogue of our good gadgets. That is, the (M, k) -good gadget in this setting guarantees that

- All leaves of T_i are in the same layer L_h .

- For each layer L_j , we have $|\mathcal{S} \cap L_j| \leq k$. For each tree T_i , for each leaf $v \in V(T_i)$, the unique path from r_i to v contains one vertex in \mathcal{S} .
- For any subset $\mathcal{B} \subseteq \{r_1, \dots, r_M\}$, for any strategy \mathcal{U} , at least $(1 - 1/k - O(1/d)) \frac{|\mathcal{B}| |L_h|}{M}$ vertices in L_h are $(\mathcal{U}, \mathcal{B})$ -risky.

This gadget can be used to recursively construct the instance in k phases. The final instance guarantees the integrality gap of $1 - (1 - 1/k)^k + O(k/d)$. By setting $k = \sqrt{d}$, we get the integrality gap of $(1 - 1/e + O(1/\sqrt{d}))$ as desired.⁷ \square

4 Hartke's Constraints

Due to the integrality gap result in the previous section, there is no hope to improve the best known algorithms via the canonical LP relaxation. Hartke [12] suggested adding the following constraints to narrow down the integrality gap of the LP.

$$\sum_{u \in P_v \cup (T_v \cap L_j)} x_u \leq 1 \text{ for each vertex } v \in V(T) \text{ and layer } L_j \text{ below the layer of } v$$

We write the new LP with these constraints below:

$$\begin{aligned}
 & \text{(LP')} \\
 & \max \sum_{v \in V} y_v \\
 & \sum_{u \in P_v \cup (T_v \cap L_j)} x_u \leq 1 \text{ for each layer } j \text{ below vertex } v \\
 & y_v \leq \sum_{u \in P_v} x_u \text{ for each } v \in V \\
 & x_v, y_v \in [0, 1] \text{ for each } v
 \end{aligned}$$

Proposition 2. *Given the values $\{x_v\}_{v \in V(T)}$ that satisfy the first set of constraints, then the solution (x, y) defined by $y_v = \sum_{u \in P_v} x_u$ is feasible for (LP') and at least as good as any other feasible (x, y') .*

In this section, we study the power of this LP and provide three evidences that it may be stronger than (LP-1).

4.1 New Properties of Extreme Points

In this section, we show that Finbow et al. tractable instances [11] admit a polynomial time exact algorithm via (LP') (in fact, any optimal extreme point for (LP') is integral.) In contrast, we show that (LP-1) contains an extreme point that is not integral.

We first present the following structural lemma.

⁷ By analyzing the Taylor's series expansion of $1/e - (1 - 1/k)^k$, we get the term $\frac{1}{2ek} + O(1/k^2)$.

Lemma 5. *Let (\mathbf{x}, \mathbf{y}) be an optimal extreme point for (LP') on instance T rooted at s . Suppose s has two children, denoted by a and b . Then $x_a, x_b \in \{0, 1\}$.*

Proof. Suppose that $x_a, x_b \in (0, 1)$. We will define two solutions $(\mathbf{x}', \mathbf{y}')$ and $(\mathbf{x}'', \mathbf{y}'')$ and derive that (\mathbf{x}, \mathbf{y}) can be written as a convex combination of $(\mathbf{x}', \mathbf{y}')$ and $(\mathbf{x}'', \mathbf{y}'')$, a contradiction.

First, we define $(\mathbf{x}', \mathbf{y}')$ by setting $x'_b = 1, x'_a = 0$. For each vertex $v \in T_b$, we set $x'_v = 0$. For each vertex $v \in T_a$, we define $x'_v = x_v/(1 - x_a)$. We verify that x' is feasible for (LP') : For each $v \in T_a$ and any layer L_j below v , $\sum_{u \in P_v} x'_u + \sum_{u \in T_v \cap L_j} x'_u = \frac{(\sum_{u \in P_v} x_u) - x_a}{(1 - x_a)} + \frac{\sum_{u \in T_v \cap L_j} x_u}{(1 - x_a)} \leq \frac{(\sum_{u \in P_v \cup (T_v \cap L_j)} x_u) - x_a}{(1 - x_a)} \leq 1$ (the last inequality is due to the fact that \mathbf{x} is feasible). The constraint is obviously satisfied for every $v \in T_b$. For the root node $v = s$, we have $\sum_{u \in L_j} x'_u = \frac{(\sum_{u \in (L_j \cap T_a)} x_u) - x_a}{(1 - x_a)} \leq 1$.

We define $(\mathbf{x}'', \mathbf{y}'')$ analogously: $x''_b = 0, x''_a = 1$. For each vertex $v \in T_a$, we set $x''_v = 0$, and for each $v \in T_b$, we define $x''_v = x_v/(1 - x_b)$. It can be checked similarly that $(\mathbf{x}'', \mathbf{y}'')$ is a feasible solution.

Claim. If \mathbf{x} is an optimal extreme point, then $x_a + x_b = 1$.

Proof. Observe that, for each $v \in T_b$, $y'_v = 1$ and for each $v \in T_a$, $y'_v = \frac{y_v - x_a}{1 - x_a}$. The objective value of \mathbf{x}' is $|T_b| + \sum_{v \in T_a} y'_v = |T_b| + \frac{1}{(1 - x_a)} \sum_{v \in T_a} (y_v - x_a) = |T_b| + \frac{\sum_{v \in T_a} y_v}{(1 - x_a)} - \frac{x_a}{(1 - x_a)} |T_a|$. Similarly, the objective value of solution \mathbf{x}'' is $|T_a| + \frac{1}{(1 - x_b)} \sum_{v \in T_b} (y_v - x_b) = |T_a| + \frac{\sum_{v \in T_b} y_v}{(1 - x_b)} - \frac{x_b}{(1 - x_b)} |T_b|$.

Consider the convex combination $\frac{1 - x_a}{(2 - x_a - x_b)} \mathbf{x}' + \frac{1 - x_b}{(2 - x_a - x_b)} \mathbf{x}''$. This solution is feasible and has the objective value of

$$\frac{1}{(2 - x_a - x_b)} \cdot \left((1 - x_a - x_b) (|T_a| + |T_b|) + \sum_{v \in V(T)} y_v \right)$$

If $x_a + x_b < 1$, we apply the fact that $|T_a| + |T_b| > \sum_{v \in V(T)} y_v$ to get the objective of strictly more than $\sum_{v \in V(T)} y_v$, contradicting the fact that (\mathbf{x}, \mathbf{y}) is optimal. \square

Finally, we define the convex combination by $\mathbf{z} = (1 - x_a) \mathbf{x}' + x_a \mathbf{x}''$. It can be verified easily that $z_v = x_v$ for every $v \in V(T)$.

Finbow et al. Instances: In this instance, the tree has degree at most 3 and the root has degree 2. Finbow et al. [11] showed that this is polynomial time solvable.

Theorem 5. *Let (T, s) be an input instance where T has degree at most 3 and s has degree two. Let (x, y) be a feasible fractional solution for (LP') . Then there is a polynomial time algorithm that saves at least $\sum_{v \in V(T)} y_v$ vertices.*

Proof. We prove this by induction on the number of nodes in the tree that, for any tree (T', s') that is a Finbow et al. instance, for any fractional solution (x, y) for (LP'), there is an integral solution (x', y') such that $\sum_{v \in T' \setminus \{s'\}} y'_v = \sum_{v \in T' \setminus \{s'\}} y_v$. Let a and b be the children of the root s . From Lemma 5, assume w.l.o.g. that $x_a = 1$, so we have $\sum_{v \in T_a} y_v = |T_a|$. By the induction hypothesis, there is an integral solution (x', y') for the subtree T_b such that $\sum_{v \in T_b} y'_v = \sum_{v \in T_b \setminus \{b\}} y'_v = \sum_{v \in T_b} y_v$. The solution (x', y') can be extended to the instance T by defining $x'_a = 1$. This solution has the objective value of $|T_a| + \sum_{v \in T_b} y'_v = |T_a| + \sum_{v \in T_b} y_b$, completing the proof.

Bad instance for (LP-1): We show in Fig. 1 a Finbow et al. instance as well as a solution for (LP-1) that is optimal and an extreme point, but not integral.

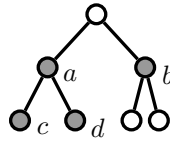


Figure 1. Instance with a non-integral extreme point for (LP-1). *Gray vertices:* $x_v = 1/2$; otherwise: $x_v = 0$.

Claim. The solution (x, y) represented in Fig. 1, with y defined according to Proposition 2, is an extreme point of this instance for (LP-1).

Proof. Suppose (for contradiction) that (x, y) is not an extreme point. Then, there are distinct solutions (x', y') , (x'', y'') and $\alpha \in (0, 1)$ such that $(x, y) = \alpha(x', y') + (1 - \alpha)(x'', y'')$. Since $y_c = 1$ and $y'_c, y''_c \leq 1$, then $y'_c = y''_c = 1$, and likewise, $y'_d = y''_d = 1$. Combining that $x'_a + x'_c = y'_c = 1$ with $x'_a + x'_d = y'_d = 1$ and $x'_c + x'_d \leq 1$, we conclude that $x'_a \geq 1/2$. Similarly, we get that $x''_a \geq 1/2$, which implies that $x'_a = x''_a = 1/2$.

Similar reasoning using that $x'_a + x'_b \leq 1$ allows us to conclude that $x'_b = x''_b = 1/2$, and thus, $(x', y') = (x'', y'') = (x, y)$, which contradicts our assumption. \square

4.2 Rounding 1/2-integral Solutions

We say that the LP solution (x, y) is $(1/k)$ -integral if, for each v , we have $x_v = r_v/k$ for some integer $r_v \in \{0, \dots, k\}$. By standard LP theory, one can assume that the LP solution is $(1/k)$ -integral for some polynomially large integer k .

In this section, we consider the case when $k = 2$ (1/2-integral LP solutions). From Theorem 2, (LP-1) is not strong enough to obtain a $3/4 + \epsilon$ approximation algorithm, for any $\epsilon > 0$. Here, we show a $5/6$ approximation algorithm based on rounding (LP').

Theorem 6. *Given a solution (x, y) for (LP') that is $1/2$ -integral, there is a polynomial time algorithm that produces a solution of cost $5/6 \sum_{v \in V(T)} y_v$.*

We believe that the extreme points in some interesting special cases will be $1/2$ -integral.

Algorithm's Description: Initially, $\mathcal{U} = \emptyset$. Our algorithm considers the layers L_1, \dots, L_n in this order. When the algorithm looks at layer L_j , it picks a vertex u_j and adds it to \mathcal{U} , as follows. Consider $A_j \subseteq L_j$, where $A_j = \{v \in L_j : x_v > 0\}$. Let $A'_j \subseteq A_j$ contain vertices v such that there is no ancestor of v that belongs to $A_{j'}$ for some $j' < j$, and $A''_j = A_j \setminus A'_j$, i.e. for each $v \in A''_j$, there is another vertex $u \in A_{j'}$ for some $j' < j$ such that u is an ancestor of v . We choose the vertex u_j based on the following rules:

- If there is only one $v \in A_j$, such that v is not saved by \mathcal{U} so far, choose $u_j = v$.
- Otherwise, if $|A'_j| = 2$, pick u_j at random from A'_j with uniform probability. Similarly, if $|A''_j| = 2$, pick u_j at random from A''_j .
- Otherwise, we have the case $|A'_j| = |A''_j| = 1$. In this case, we pick vertex u_j from A'_j with probability $1/3$; otherwise, we take from A''_j .

Analysis: Below, we argue that each vertex $v \in V(T) : x_v > 0$ is saved with probability at least $(5/6)y_v$. It is clear that this implies the theorem: Consider a vertex $v' : x_{v'} = 0$. If $y_{v'} = 0$, we are immediately done. Otherwise, consider the bottommost ancestor v of v' such that $x_v > 0$. Since $y_v = y_{v'}$, the probability that v' is saved is the same as that of v , which is at least $(5/6)y_v$.

We analyze a number of cases. Consider a layer L_j such that $|A_j| = 1$. Such a vertex $v \in A_j$ is saved with probability 1.

Next, consider a layer L_j such that $|A'_j| = 2$. Each vertex $v \in A'_j$ is saved with probability $1/2$ and $y_v = 1/2$. So, in this case, the probability of saving v is more than $(5/6)y_v$.

Lemma 6. *Let L_j be the layer such that $|A'_j| = |A''_j| = 1$. Then the vertex $u \in A'_j$ is saved with probability $2/3 \geq (5/6)y_u$ and vertex $v \in A''_j$ is saved with probability $5/6$.*

Proof. Let $v' \in A_{j'}$ be the ancestor of v in some layer above A_j . The fact that v has not been saved means that v' is not picked by the algorithm, when it processed $A_{j'}$.

We prove the lemma by induction on the value of j . For the base case, let L_j be the first layer such that $|A'_j| = |A''_j| = 1$. This means that the layer $L_{j'}$ must have $|A'_{j'}| = 2$, and therefore the probability of v' being saved is at least $1/2$. Vertex u is not saved only if both v' and u are not picked, and this happens with probability $1/2 \cdot 2/3 = 1/3$. Hence, vertex u is saved with probability $2/3$ as desired. Consider now the base case for vertex v , which is not saved only if v' is not saved and u is picked by the algorithm among $\{u, v\}$. This happens with probability $1/2 \cdot 1/3 = 1/6$, thus completing the proof of the base case.

For the purpose of induction, we now assume that, for each layer L_i above L_j such that $|A'_i| = |A''_i| = 1$, the probability that the algorithm saves the vertex in A'_i is at least $2/3$. Since the vertex u is not saved only if v' is not saved, this probability is either $1/2$ or $1/3$ depending on the layer to which v' belongs. If it is $1/3$, we are done; otherwise, the probability is at most $1/2 \cdot 2/3 = 1/3$. Now consider vertex v , which is not saved only if v' is not saved and u is picked at L_j . This happens with probability at most $1/2 \cdot 1/3 = 1/6$. \square

Lemma 7. *Let L_j be a layer such that $A''_j = \{u, v\}$ (containing two vertices). Then each such vertex is saved with probability at least $5/6$.*

Proof. Let u' and v' be the ancestors of u and v in some sets A'_i and A'_k above the layer L_j . There are the two possibilities: either both u' and v' are in layers with $|A'_i| = |A'_k| = 2$ (maybe $i = k$); or u' is in the layer with $|A'_i| = |A''_i| = 1$. We remark that $u' \neq v'$: otherwise, the LP constraint for v' and L_j would not be satisfied.

For u or v to be unsaved, we need that both u' and v' are not saved by the algorithm. Otherwise, if, say, u' is saved, u is also saved, and the algorithm would have picked v .

$$\begin{aligned} P[u \text{ is not saved}] &= P[u \text{ not picked} \wedge u' \text{ is not saved} \wedge v' \text{ is not saved}] \\ &= P[u \text{ not picked}] \cdot P[u' \text{ is not saved} \wedge v' \text{ is not saved}] \\ &= \frac{1}{2} \cdot \frac{1}{4} = \frac{1}{8} \\ P[u \text{ is saved}] &= \frac{7}{8} \geq \frac{5}{6} \end{aligned}$$

It must be that $P[u' \text{ burns} \wedge v' \text{ burns}] \leq 1/4$, since either u' and v' are in different layers or they are in the same layer. If they are in different layers, picking each of them is independent, and the probability of neither being saved is at most $1/4$. If they are in the same layer, one of them is necessarily picked, which implies that the probability of neither being saved is 0. In any case, the probability is at most $1/4$.

In the second case, at least one of the vertices u' , v' is in a layer with one 2-special vertex. W. l. o. g. let u' be in such a layer. By Lemma 6, we know that the probability that u' is not saved is at most $1/3$. Therefore,

$$\begin{aligned} P[u \text{ burns}] &= P[u \text{ not picked} \wedge u' \text{ burns} \wedge v' \text{ burns}] \\ &= P[u \text{ not picked}] \cdot P[u' \text{ burns} \wedge v' \text{ burns}] \\ &\leq P[u \text{ not picked}] \cdot P[u' \text{ burns}] \\ &\leq \frac{1}{2} \cdot \frac{1}{3} = \frac{1}{6} \\ P[u \text{ is saved}] &\geq \frac{5}{6} \end{aligned}$$

The proof for both cases works analogously for v . \square

4.3 Ruling Out the Gap Instances in Section 3

In this section, we show that the integrality gap instances for (LP-1) presented in the previous section admit a better than $(1 - 1/e)$ approximation via (LP'). To this end, we introduce the concept of well-separable LP solutions and show an improved rounding algorithm for solutions in this class.

Let $\eta \in (0, 1)$. Given an LP solution (x, y) for (LP-1) or (LP'), we say that a vertex v is η -light if $\sum_{u \in P_v \setminus \{v\}} x_u < \eta$; if a vertex v is not η -light, we say that it is η -heavy. A fractional solution is said to be η -separable if for each layer j , either all vertices in L_j are η -light, or they are all η -heavy. For an η -separable LP solution (x, y) , each layer L_j is either an η -light layer that contains only η -light vertices, or η -heavy layer that contains only η -heavy vertices.

Observation 2. *The LP solution presented in Sect. 3 is η -separable for all values of $\eta \in \{1/k, 2/k, \dots, 1\}$.*

Theorem 7. *If the LP solution (x, y) is η -separable for some η , then there is an efficient algorithm that produces an integral solution of cost $(1 - 1/e + f(\eta)) \sum_v y_v$, where $f(\eta)$ is some function depending only on η .*

Algorithm: Let T be an input tree, and (x, y) be a solution for (LP') on T that is η -separable for some constant $\eta \in (0, 1)$. Our algorithm proceeds in two phases. In the first phase, it performs randomized rounding independently for each η -light layer. Denote by V_1 the (random) collection of vertices selected in this phase. Then, in the second phase, our algorithm performs randomized rounding conditioned on the solutions in the first phase. In particular, when we process each η -heavy layer L_j , let \tilde{L}_j be the collection of vertices that have not yet been saved by V_1 . We sample one vertex $v \in \tilde{L}_j$ from the distribution $\left\{ \frac{x_v}{x(\tilde{L}_j)} \right\}_{v \in \tilde{L}_j}$. Let V_2 be the set of vertices chosen from the second phase. This completes the description of our algorithm.

For notational simplification, we present the proof when $\eta = 1/2$. It will be relatively obvious that the proof can be generalized to work for any η . Now we argue that each terminal $t \in \mathcal{X}$ is saved with probability at least $(1 - 1/e + \delta)y_t$ for some universal constant $\delta > 0$ that depends only on η . We will need the following simple observation that follows directly by standard probabilistic analysis.

Proposition 3. *For each vertex $v \in V(T)$, the probability that v is not saved is at most $\prod_{u \in P_v} (1 - x_u) \geq 1 - e^{-y_v}$.*

We start by analyzing two easy cases.

Lemma 8. *Consider $t \in \mathcal{X}$. If $y_t < 0.9$ or there is some ancestor $v \in P_t$ such that $x_v > 0.2$, then the probability that v is saved by the algorithm is at least $(1 - 1/e + \delta)y_t$.*

Proof. First, let us consider the case where $y_t < 0.9$. The probability of t being saved is at least $1 - e^{-y_v}$, according to the straightforward analysis. If $y_t < 0.9$, we have $1 - e^{-y_t}/y_t > 1.04(1 - 1/e)y_t$ as desired.

Consider now the second case when $x_v > 0.2$ for some ancestor $v \in P_t$. The bound used typically in the analysis is only tight when the values are all small, and, therefore, we get an advantage when one of the values is relatively big. In particular,

$$\begin{aligned} \Pr [t \text{ is saved}] &\geq 1 - \prod_{u \in P_t} (1 - x_u) \\ &\geq 1 - (1 - x_v)e^{-(y_t - x_v)} \\ &\geq 1 - (1 - 0.2)e^{-(y_t - 0.2)} \\ &\geq 1.01(1 - 1/e)y_v \end{aligned}$$

□

From now on, we only consider those terminals $t \in \mathcal{X}$ such that $y_t \geq 0.9$ and $x_v < 0.2$, for every $v \in P_t$. We remark here that if the value of η is not $1/2$, we can easily pick other suitable thresholds instead of 0.9 and 0.2 .

For each vertex $v \in V$, let $\mathcal{X}_1 \subseteq \mathcal{X}$ be the set of terminals that are saved by V_1 , i.e. a vertex $t \in \mathcal{X}_1$ if and only if t is a descendant of some vertex in V_1 . Let $\mathcal{X}_2 \subseteq \mathcal{X} \setminus \mathcal{X}_1$ contain the set of terminals that are not saved by the first phase, but are saved by the second phase, i.e. $t \in \mathcal{X}_2$ if and only if t has some ancestor in V_2 .

$$\Pr_{V_1, V_2} [t \notin \mathcal{X}_1 \cup \mathcal{X}_2] = \Pr_{V_1, V_2} [t \notin \mathcal{X}_1] \Pr_{V_1, V_2} [t \notin \mathcal{X}_2 : t \notin \mathcal{X}_1]$$

For any terminal t , let \mathcal{S}'_t and \mathcal{S}''_t be the sets of ancestors of t that are η -light and η -heavy respectively, i.e. ancestors in \mathcal{S}'_t and \mathcal{S}''_t are considered by the algorithm in Phase 1 and 2 respectively. By Proposition 3, we can upper bound the first term by $e^{-x(\mathcal{S}'_t)}$. In the rest of this section, we show that the second term is upper bounded by $e^{-x(\mathcal{S}''_t)}c$ for some $c < 1$, and therefore $\Pr [t \notin \mathcal{X}_1 \cup \mathcal{X}_2] \leq ce^{-x(\mathcal{S}'_t) - x(\mathcal{S}''_t)} \leq ce^{-y_t}$, as desired.

The following lemma is the main technical tool we need in the analysis. We remark that this lemma is the main difference between (LP') and (LP-2).

Lemma 9. *Let $t \in \mathcal{X}$ and L_j be a layer containing some η -heavy ancestor of t . Then*

$$\mathbb{E}_{V_1} [x(\tilde{L}_j) \mid t \notin \mathcal{X}_1] \leq \alpha$$

$$\text{for } \alpha = \frac{1}{2} + (1 - e^{-1/2}) \leq 0.9$$

Intuitively, this lemma says that any terminal that is still not saved by the result of the first phase will have a relatively “sparse” layer above it. We defer the proof of this lemma to the next subsection. Now we proceed to complete the analysis.

For each vertex v , denote by $\ell(v)$ the layer to which vertex v belongs. For a fixed choice of V_1 , we say that terminal t is *partially protected* by V_1 if $\sum_{v \in \mathcal{S}_t''} x_v x(\tilde{L}_{\ell(v)}) \leq Cx(\mathcal{S}_t'')$ (we will choose the value of $C \in (\alpha, 1)$ later). Let $\mathcal{X}' \subseteq \mathcal{X} \setminus \mathcal{X}_1$ denote the subset of terminals that are partially protected by V_1 .

Claim. For any $t \in \mathcal{X}$, $\Pr_{V_1}[t \in \mathcal{X}' \mid t \notin \mathcal{X}_1] \geq 1 - \alpha/C$.

Proof. By linearity of expectation and Lemma 9,

$$\mathbf{E}_{V_1} \left[\sum_{v \in \mathcal{S}_t''} x_v x(\tilde{L}_{\ell(v)}) \mid t \notin \mathcal{X}_1 \right] = \sum_{v \in \mathcal{S}_t''} x_v \mathbf{E}_{V_1} [x(\tilde{L}_{\ell(v)}) \mid t \notin \mathcal{X}_1] \leq \alpha x(\mathcal{S}_t'')$$

Using Markov's inequality,

$$\begin{aligned} \Pr_{V_1} \left[\sum_{v \in \mathcal{S}_t''} x_v x(\tilde{L}_{\ell(v)}) \leq Cx(\mathcal{S}_t'') \mid t \notin \mathcal{X}_1 \right] \\ &= 1 - \Pr \left[\sum_{v \in \mathcal{S}_t''} x_v x(\tilde{L}_{\ell(v)}) > Cx(\mathcal{S}_t'') \mid t \notin \mathcal{X}_1 \right] \\ &\geq 1 - \frac{\alpha x(\mathcal{S}_t'')}{Cx(\mathcal{S}_t'')} \\ &= 1 - \frac{\alpha}{C} \end{aligned}$$

□

We can now rewrite the probability of a terminal $t \in \mathcal{X}$ not being saved by the solution after the second phase.

$$\begin{aligned} &\Pr_{V_1, V_2} [t \notin \mathcal{X}_2 \mid t \notin \mathcal{X}_1] \\ &= \Pr [t \in \mathcal{X}' \mid t \notin \mathcal{X}_1] \Pr [t \notin \mathcal{X}_2 \mid t \in \mathcal{X}'] + \Pr [t \notin \mathcal{X}' \mid t \notin \mathcal{X}_1] \Pr [t \notin \mathcal{X}_2 \mid t \notin \mathcal{X}'] \\ &\leq (1 - \alpha/C) \Pr_{V_1, V_2} [t \notin \mathcal{X}_2 \mid t \in \mathcal{X}'] + \frac{\alpha}{C} \cdot e^{-x(\mathcal{S}_t'')} \end{aligned}$$

The last inequality holds because $\Pr_{V_1, V_2} [t \notin \mathcal{X}_2 \mid t \in \mathcal{X}']$ is at most $e^{-x(\mathcal{S}_t'')}$ from Proposition 3.

It remains to provide a better upper bound for $\Pr [t \notin \mathcal{X}_2 \mid t \in \mathcal{X}']$. Consider a vertex $v \in \mathcal{S}_t''$ that is involved in the second phase rounding. We say that vertex v is *good* for t and V_1 if $x(\tilde{L}_{\ell(v)}) \leq C'$ (we will choose the value $C' \in (C, 1)$ later.) Denote by $\mathcal{S}_t^{\text{good}} \subseteq \mathcal{S}_t''$ the set of good ancestors of t . The following claim ensures that good ancestors have large LP-weight in total.

Claim. For any node $t \in \mathcal{X}'$, $x(\mathcal{S}_t^{\text{good}}) = \sum_{v \in \mathcal{S}_t^{\text{good}}} x_v \geq (1 - C/C')x(\mathcal{S}_t'')$.

Proof. Suppose (for contradiction) that the fraction of good layers was less than $1 - C/C'$. This means that $x(\mathcal{S}_t'' \setminus \mathcal{S}_t^{\text{good}}) \geq C/C'$. For each such $v \in \mathcal{S}_t'' \setminus \mathcal{S}_t^{\text{good}}$, we have $x(\tilde{L}(v)) > C'$. Then, $\sum_{v \in \mathcal{S}_t''} x_v x(\tilde{L}(v)) > \sum_{v \in \mathcal{S}_t'' \setminus \mathcal{S}_t^{\text{good}}} x_v C' \geq C$. This contradicts the assumption that t is partially protected, and concludes our proof. \square

Now the following lemma follows.

Lemma 10. $\Pr_{V_1, V_2} [t \notin \mathcal{X}_2 \mid t \in \mathcal{X}'] \leq e^{-x(\mathcal{S}_t'')} e^{-(1-\frac{C}{C'})x(\mathcal{S}_t'')(\frac{1}{C'}-1)}$

Proof.

$$\begin{aligned}
& \Pr_{V_1, V_2} [t \notin \mathcal{X}_2 \mid t \in \mathcal{X}'] \\
&= \sum_{V_1': t \in \mathcal{X}'} \Pr_{V_1} [V_1 = V_1'] \Pr_{V_2} [t \notin \mathcal{X}_2 \mid V_1 = V_1'] \\
&\leq \sum_{V_1': t \in \mathcal{X}'} \Pr_{V_1} [V_1 = V_1'] \prod_{\text{bad } v \in \mathcal{S}_t''} (1 - x_v) \prod_{\text{good } v \in \mathcal{S}_t''} \left(1 - \frac{x_v}{C'}\right) \\
&\leq \sum_{V_1': t \in \mathcal{X}'} \Pr_{V_1} [V_1 = V_1'] \prod_{\text{bad } v \in \mathcal{S}_t''} e^{-x_v} \prod_{\text{good } v \in \mathcal{S}_t''} e^{-x_v/C'} \\
&\leq \sum_{V_1': t \in \mathcal{X}'} \Pr_{V_1} [V_1 = V_1'] e^{-x(\mathcal{S}_t'')\frac{C}{C'} - (1-C/C')x(\mathcal{S}_t'')/C'} \\
&\leq e^{-x(\mathcal{S}_t'')\frac{C}{C'} - (1-C/C')x(\mathcal{S}_t'')/C'} \sum_{V_1': t \in \mathcal{X}'} \Pr_{V_1} [V_1 = V_1'] \\
&\leq e^{-x(\mathcal{S}_t'')\frac{C}{C'} - (1-C/C')x(\mathcal{S}_t'')/C'} \\
&\leq e^{-x(\mathcal{S}_t'')} e^{-(1-C/C')x(\mathcal{S}_t'')(\frac{1}{C'}-1)}
\end{aligned}$$

\square

Now we choose the parameters C and C' such that $C = (1 + \delta)\alpha$, $C' = (1 + \delta)C$, and $(1 + \delta)C' = 1$, where $(1 + \delta)^3 = 1/\alpha$. Notice that this choice of parameters satisfy our previous requirements that $\alpha < C < C' < 1$. The above lemma then gives the upper bound of $e^{-x(\mathcal{S}_t'')} e^{-\frac{\delta^2}{1+\delta}x(\mathcal{S}_t'')}$, which is at most $e^{-(1+\delta^2/2)x(\mathcal{S}_t'')}$. Since $\delta > 0$ is a constant, notice that we do have an advantage over the standard LP rounding in this case. Now we plug in all the parameters to obtain the final result.

$$\begin{aligned}
\Pr_{V_1, V_2} [t \notin \mathcal{X}_1 \cup \mathcal{X}_2] &= \Pr_{V_1, V_2} [t \notin \mathcal{X}_1] \Pr_{V_1, V_2} [t \notin \mathcal{X}_2 \mid t \notin \mathcal{X}_1] \\
&\leq e^{-x(\mathcal{S}_t)} \left((1 - \alpha/C) \Pr_{V_1, V_2} [t \notin \mathcal{X}_2 \mid t \in \mathcal{X}'] + \frac{\alpha}{C} e^{-x(\mathcal{S}_t')} \right) \\
&\leq e^{-x(\mathcal{S}_t)} \left((1 - \alpha/C) e^{-x(\mathcal{S}_t')} e^{-\frac{\delta^2}{2} x(\mathcal{S}_t')} + \frac{\alpha}{C} e^{-x(\mathcal{S}_t')} \right) \\
&\leq e^{-y_t} \left((1 - \alpha/C) e^{-\frac{\delta^2}{2} x(\mathcal{S}_t')} + \alpha/C \right) \\
&\leq e^{-y_t} \left(\frac{\delta}{1 + \delta} e^{-(1 + \delta^2/2)x(\mathcal{S}_t')} + \frac{1}{1 + \delta} \right)
\end{aligned}$$

Since we assume that $y_t > 0.9$ and $x_v \leq 0.2$, we must have $x(\mathcal{S}_t') \geq 0.2$, and therefore the above term can be seen as $e^{-y_t} \cdot \delta'$ for some $\delta' < 1$. Overall, the approximation factor we get is $(1 - \delta'/e)$ for some universal constant $\delta' \in (0, 1)$.

Proof of Lemma 9 For each u , let \mathcal{E}_u denote the event that u is not saved by V_1 . First we break the expectation term into $\sum_{u \in L_j} x_u \Pr [\mathcal{E}_u \mid t \notin \mathcal{X}_1]$. Let $v \in L$ be the ancestor of t in layer L_j . We break down the sum further based on the ‘‘LP coverage’’ of the least common ancestor between u and v , as follows:

$$\sum_{i=0}^{k/2} \sum_{u \in L_j: q'(lca(u, v))=i} x_u \Pr [\mathcal{E}_u \mid t \notin \mathcal{X}_1]$$

Here, $q'(u)$ denotes $k \cdot x(P_u)$; this term is integral since we consider the $1/k$ -integral solution (x, y) . The rest of this section is devoted to upper bounding the term $\Pr [\mathcal{E}_u \mid t \notin \mathcal{X}_1]$. The following claim gives the bound based on the level i to which the least common ancestor belongs.

Claim. For each $u \in L_j$ such that $q'(lca(u, v)) = i$,

$$\Pr [\mathcal{E}_u \mid t \notin \mathcal{X}_1] \leq e^{-(1/2 - i/k)}$$

Proof. First, we recall that $y_u \geq 1/2$ and $q'(u) \geq k/2$, since u is in the $1/2$ -heavy layer L_j . Let $w = lca(u, v)$ and P' be the path that connects w to u . Moreover, denote by $S \subseteq P'$ the set of light vertices on the path P' , i.e. $S = \mathcal{S}'_t \cap P'$. Notice that $x(S) \geq \sum_{a \in \mathcal{S}'_t \cap P_u} x_a - \sum_{a \in P_w} x_a \geq (1/2 - i/k)$.

For each $w' \in S$, $\Pr [w' \notin V_1 \mid t \notin \mathcal{X}_1] \in \{1 - x_{w'}, 1 - x_{w'}/(1 - x_{v'})\}$ depending on whether there is a vertex v' in P_v that shares a layer with w' . In any case, it holds that $\Pr [w' \notin V_1 \mid t \notin \mathcal{X}_1] \leq (1 - x_{w'})$. This implies that

$$\begin{aligned}
\Pr [\mathcal{E}_u \mid t \notin \mathcal{X}_1] &\leq \prod_{w' \in S} \Pr [w' \notin V_1 \mid t \notin \mathcal{X}_1] \\
&\leq \prod_{w' \in S} (1 - x_{w'}) \\
&\leq \prod_{w' \in S} e^{-x_{w'}} \\
&\leq e^{-(1/2 - i/k)}
\end{aligned}$$

□

Claim. Let i be an integer and $L' \subseteq L_j$ be the set of vertices u such that $q'(lca(u, v))$ is at least i . Then $x(L') \leq (k - i)/k$.

Proof. This claim is a consequence of Hartke's constraints. Let v' be the topmost ancestor of v such that $q'(v') \geq i$. We remark that all vertices in L' must be descendants of v' , so it must be that $\sum_{w \in P_{v'}} x_w + x(L') \leq 1$. The first term is i/k , implying that $x(L') \leq (k - i)/k$. □

Let $L_j^i \subseteq L_j$ denote the set of vertices u whose least common ancestor $lca(u, v)$ satisfies $q'(lca(u, v)) = i$. As a consequence of Claim 4.3, $\sum_{i' \geq i} x(L_j^{i'}) \leq (k - i)/k$. Combining this inequality with Claim 4.3, we get that

$$\mathbf{E} \left[x(\tilde{L}_j) \mid t \notin \mathcal{X}_1 \right] \leq \sum_{i=0}^{k/2} x(L_j^i) e^{-1/2+i/k}$$

This term is maximized when $x(L_j^{k/2}) = 1/2$ and $x(L_j^i) = 1/k$ for all other $i = 0, 1, \dots, k/2 - 1$. This implies that

$$\mathbf{E} \left[x(\tilde{L}_j) \mid t \notin \mathcal{X}_1 \right] \leq 1/2 + \sum_{i=0}^{k/2-1} e^{-1/2+i/k} / k$$

Finally, using some algebraic manipulation and the fact that $1 + x \leq e^x$, we get

$$\begin{aligned} \mathbf{E} \left[x(\tilde{L}_j) \mid t \notin \mathcal{X}_1 \right] &\leq 1/2 + \sum_{i=0}^{k/2-1} e^{-1/2+i/k} / k \\ &= 1/2 + \frac{1}{k} e^{-1/k} \frac{1 - e^{-1/2}}{1 - e^{-1/k}} \\ &= 1/2 + (1 - e^{-1/2}) \frac{1}{e^{1/k}} \frac{1/k}{1 - e^{-1/k}} \\ &= 1/2 + (1 - e^{-1/2}) \frac{1/k}{e^{1/k} - 1} \\ &\leq 1/2 + (1 - e^{-1/2}) \end{aligned}$$

4.4 Integrality Gap for (LP')

In this section, we present an instance where (LP') has an integrality gap of $5/6 + \epsilon$, for any $\epsilon > 0$. Interestingly, this instance admits an optimal $\frac{1}{2}$ -integral LP solution.

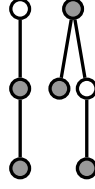


Figure 2. Gadget used to get $5/6$ integrality gap. Special vertices are colored *gray*.

Gadget: The motivation of our construction is a simple gadget represented in Fig. 2. In this instance, vertices are either *special* (colored gray) or *regular*. This gadget has three properties of our interest:

- If we assign an LP-value of $x_v = 1/2$ to every special vertex, then this is a feasible LP solution that ensures $y_u = 1$ for every leaf u .
- For any integral solution \mathcal{U} that does not pick any vertex in the first layer of this gadget, at most 2 out of 3 leaves of the gadget are saved.
- Any pair of special vertices in the same layer do not have a common ancestor inside this gadget.

Our integrality gap instance is constructed by creating partially overlapping copies of this gadget. We describe it formally below.

Construction: The first layer of this instance, L_1 , contains 4 nodes: two special nodes, which we name $a(1)$ and $a(2)$, and two regular nodes, which we name $b(1)$ and $b(2)$. We recall the definition of spider from Sect. 3.1.

Let $\alpha = 5 \lceil 1/\epsilon \rceil$. The nodes $b(1)$ and $b(2)$ are the roots of two spiders. Specifically, the spider Z_1 rooted at $b(1)$ has α feet, with one foot per layer, in consecutive layers $L_2, \dots, L_{\alpha+1}$. For each $j \in [\alpha]$, denote by $b'(1, j)$, the j^{th} foot of spider Z_1 . The spider Z_2 , rooted at $b(2)$, has α^2 feet, with one foot per layer, in layers $L_{\alpha+2}, \dots, L_{\alpha^2+\alpha+1}$. For each $j \in [\alpha^2]$, denote by $b'(2, j)$, the j^{th} foot of spider Z_2 . All the feet of spiders Z_1 and Z_2 are special vertices.

For each $j \in [\alpha]$, the node $b'(1, j)$ is also the root of spider $Z'_{1,j}$, with α^2 feet, lying in the α^2 consecutive layers $L_{2+\alpha+j\alpha^2}, \dots, L_{1+\alpha+(j+1)\alpha^2}$ (one foot per layer). For $j' \in [\alpha^2]$, let $b''(1, j, j')$ denote the j' -th foot of spider $Z'_{1,j}$ that lies in layer $L_{1+\alpha+j\alpha^2+j'}$. Notice that we have α^3 such feet of these spiders $\{Z'_{1,j}\}_{j=1}^{\alpha}$ lying in layers $L_{2+\alpha+\alpha^2}, \dots, L_{1+\alpha+\alpha^2+\alpha^3}$. Similarly, for each $j \in [\alpha^2]$, the node $b'(2, j)$ is the root of spider $Z'_{2,j}$ with α^2 feet, lying in consecutive layers $L_{2+\alpha+\alpha^3+j\alpha^2}, \dots, L_{1+\alpha+\alpha^3+(j+1)\alpha^2}$. We denote by $b''(2, j, j')$ the j' -th foot of this spider.

The special node $a(1)$ is also the root of spider W_1 which has $\alpha + \alpha^3$ feet: The first α feet, denoted by $a'(1, j)$ for $j \in [\alpha]$, are aligned with the nodes $b'(1, j)$, i.e. for each $j \in [\alpha]$, the foot $a'(1, j)$ of spider W_1 is in the same layer as the foot $b'(1, j)$ of Z_1 . For each $j \in [\alpha], j' \in [\alpha^2]$, we also have a foot $a''(1, j, j')$ which is placed in the same layer as $b''(1, j, j')$. Similarly, the special node $a(2)$ is the

root of spider W_2 having $\alpha^2 + \alpha^4$ feet. For $j \in [\alpha^2]$, spider W_2 has a foot $a'(2, j)$ placed in the same layer as $b'(2, j)$. For $j \in [\alpha^2], j' \in [\alpha^2]$, W_2 also has a foot $a''(2, j, j')$ in the layer of $b''(2, j, j')$. All the feet of both W_1 and W_2 are special vertices.

Finally, for $i \in \{1, 2\}$, and $j \in [\alpha^i]$, each node $a'(i, j)$ has α^{5-i} children, which are leaves of the instance. For $j \in [\alpha], j' \in [\alpha^2]$, the nodes $b''(i, j, j')$, $a''(i, j, j')$ have α^{3-i} children each which are also leaves of the instance. The set of terminals \mathcal{X} is simply the set of leaves.

Proposition 4. *We have $|\mathcal{X}| = 6\alpha^5$. Moreover, (i) the number of terminals in subtrees $T_{a(1)} \cup T_{b(1)}$ is $3\alpha^5$, and (ii) the number of terminals in subtrees $T_{a(2)} \cup T_{b(2)}$ is $3\alpha^5$.*

Proof. Each node $a'(1, j)$ has α^4 children, and there are α such nodes. Similarly, each node $a'(2, j)$ has α^3 children. There are α^2 such nodes. This accounts for $2\alpha^5$ terminals.

For $i \in \{1, 2\}$, each node $a''(i, j, j')$ has α^{3-i} children. There are α^{i+2} such nodes. This accounts for another $2\alpha^5$ terminals. Finally, there are α^{3-i} children of each $b''(i, j, j')$, and there are α^{2+i} such nodes.

Fractional Solution: Our construction guarantees that any path from root to leaf contains 2 special vertices: For a leaf child of $a'(i, j)$, its path towards the root must contain $a'(i, j)$ and $a(i)$. For a leaf child of $a''(i, j, j')$, its path towards the root contains $a''(i, j, j')$ and $a(i)$. For a leaf child of $b''(i, j, j')$, the path towards the root contains $b''(i, j, j')$ and $b'(i, j)$.

Lemma 11. *For each special vertex v , for each layer L_j below v , the set $L_j \cap T_v$ contains at most one special vertex.*

Proof. Each layer contains two special vertices of the form $\{a'(i, j), b'(i, j')\}$ or $\{a''(i, j), b''(i, j')\}$. In any case, the least common ancestor of such two special vertices in the same layer is always the root s (since one vertex is in $T_{a(i)}$, while the other is in $T_{b(i)}$) This implies that, for any non-root vertex v , the set $L_j \cap T_v$ can contain at most one special vertex.

Notice that, there are at most two special vertices per layer. We define the LP solution x , with $x_v = 1/2$ for every special vertex v and $x_v = 0$ for all other vertices. It is easy to verify that this is a feasible solution.

We now check the constraint at v and layer L_j below v : If the sum $\sum_{u \in P_v} x_u = 0$, then the constraint is immediately satisfied, because $\sum_{u \in L_j \cap T_v} x_u \leq 1$. If $\sum_{u \in P_v} x_u = 1/2$, let v' be the special vertex ancestor of v . Lemma 11 guarantees that $\sum_{u \in L_j \cap T_v} x_u \leq \sum_{u \in L_j \cap T_{v'}} x_u \leq 1/2$, and therefore the constraint at v and L_j is satisfied. Finally, if $\sum_{u \in P_v} x_u = 1$, there can be no special vertex below v and therefore $\sum_{u \in L_j \cap T_v} x_u = 0$.

Integral Solution: We argue that any integral solution cannot save more than $(1 + 5/\alpha)5\alpha^5$ terminals. The following lemma is the key to our analysis.

Lemma 12. *Any integral solution $\mathcal{U} : \mathcal{U} \cap \{a(1), b(1)\} = \emptyset$ saves at most $(1 + 5/\alpha)5\alpha^5$ terminals.*

Proof. Consider the set $Q = \{a'(1, j)\}_{j=1}^\alpha \cup \{b'(1, j)\}_{j=1}^\alpha$, and a collection of paths from $\{a(1), b(1)\}$ to vertices in set Q . These paths are contained in the layers $L_1, \dots, L_{\alpha+1}$, so the strategy \mathcal{U} induces a cut of size at most $\alpha + 1$ on them. This implies that at most $\alpha + 1$ vertices (out of 2α vertices in Q) can be saved by \mathcal{U} . Let $\tilde{Q} \subseteq Q$ denote the set of vertices that have not been saved by \mathcal{U} . We remark that $|\tilde{Q}| \geq \alpha - 1$. We write $\tilde{Q} = \tilde{Q}_a \cup \tilde{Q}_b$ where \tilde{Q}_a contains the set of vertices $a'(1, j)$ that are not saved, and $\tilde{Q}_b = \tilde{Q} \setminus \tilde{Q}_a$. For each vertex in \tilde{Q}_a , at least $\alpha^4 - 1$ of its children cannot be saved, so we have at least $(\alpha^4 - 1)|\tilde{Q}_a| \geq \alpha^4|\tilde{Q}_a| - \alpha$ unsaved terminals that are descendants of \tilde{Q}_a . If $|\tilde{Q}_b| \leq 3$, we are immediately done: We have $|\tilde{Q}_a| \geq \alpha - 4$, so $(\alpha^4 - 1)(\alpha - 4) \geq \alpha^5 - 5\alpha^4$ unsaved terminals.

Consider the set

$$R = \left(\bigcup_{j \in [\alpha], j' \in [\alpha^2]} \{a''(1, j, j')\} \right) \cup \left(\bigcup_{j: b'(1, j) \in \tilde{Q}_b} \bigcup_{j' \in [\alpha^2]} \{b''(1, j, j')\} \right)$$

This set satisfies $|R| = \alpha^3 + |\tilde{Q}_b|\alpha^2$, and the paths connecting vertices in R to $\tilde{Q}_b \cup \{a(1)\}$ lie in layers $L_1, \dots, L_{\alpha^3 + \alpha^2 + \alpha + 1}$. So the strategy \mathcal{U} induced on these paths disconnects at most $\alpha^3 + \alpha^2 + \alpha + 1$ vertices. Let $\tilde{R} \subseteq R$ contain the vertices in R that are not saved by \mathcal{U} , so we have $|\tilde{R}| \geq (|\tilde{Q}_b| - 1)\alpha^2 - \alpha - 1$, which is at least $(|\tilde{Q}_b| - 2)\alpha^2$. Each vertex in \tilde{R} has α^2 children. We will have $(\alpha^2 - 1)$ unsaved terminals for each such vertex, resulting in a total of at least $(\alpha^2 - 1)(|\tilde{Q}_b| - 2)\alpha^2 \geq \alpha^4|\tilde{Q}_b| - 4\alpha^4$ terminals that are descendants of $b(1)$.

In total, by summing the two cases, at least $(\alpha^4|\tilde{Q}_a| - \alpha) + (\alpha^4|\tilde{Q}_b| - 4\alpha^4) \geq (|\tilde{Q}_a| + |\tilde{Q}_b|)\alpha^4 - 5\alpha^4 \geq \alpha^5 - 5\alpha^4$ terminals are not saved by \mathcal{U} , thus concluding the proof.

Lemma 13. *Any integral solution $\mathcal{U} : \mathcal{U} \cap \{a(2), b(2)\} = \emptyset$ saves at most $(1 + 5/\alpha)5\alpha^5$ terminals.*

Since nodes $a(1)$, $a(2)$, $b(1)$, $b(2)$ are in the first layer, it is only possible to save one of them. Therefore, either Lemma 12 or Lemma 13 apply, which concludes the analysis.

5 Conclusion and Open Problems

In this paper, we settled the integrality gap question for the standard LP relaxation. Our results ruled out the hope to use the canonical LP to obtain better approximation results. While a recent paper settled the approximability status of the problem [1], the question whether an improvement over $(1 - 1/e)$ can be done via LP relaxation is of independent interest. We provide some evidences

that Hartke’s LP is a promising candidate for doing so. Another interesting question is to find a more general graph class that admits a constant approximation algorithm. We believe that this is possible for bounded treewidth graphs.

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